

Utility Indifference Pricing Methods for Incomplete Markets

Michel Vellekoop
(joint work with Marcellino Gaudenzi)

University of Amsterdam



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Motivation

- Pricing in incomplete market of new asset: **utility indifference pricing principle**
- Requires that we solve two (nonlinear) optimization problems:
$$\text{Optimized expected utility of terminal wealth including asset} = \text{Optimized expected utility of terminal wealth without asset}$$
- Hardly any closed-form solutions. See for example (Duffie et al. 1997, Cvitanic et al. 2001, Musiela & Zariphopoulou, 2004, Carmona, 2009).

Preferences

Closed-form solutions that exist in continuous time for optimal portfolio problem are often based on

- invariance in optimized **preference structure** and
- suitable **stochastic dynamics**.

Example:

CRRA utility on \mathbb{R}^+ (Merton, 1969): for $0 < \gamma \neq 1$

$$\begin{aligned}
 V_T(w) &= U_\gamma(w) := \frac{w^{1-\gamma}}{1-\gamma} \\
 \Rightarrow V_t(w) &= a(t)U_\gamma(w).
 \end{aligned}$$

Motivation

- Goal: to calculate **exact** optimal investment strategies for
 - discrete time Markov process and
 - simple preference structuresthat are 'close to' a given specification.
- Risk aversion parameter and parameters for dynamics of risk factors are difficult to measure exactly anyway.

Asset Dynamics

We use the following model:

- Discrete Markov dynamics (t, S_t, Y_t) for risky asset S and other (untradeable) risk factors Y on finite state space

$$\mathcal{T} = \bigcup_{m=0}^n \mathcal{T}_m, \quad \mathcal{T}_m = \bigcup_{k=0}^m \bigcup_{j=0}^m \{(m\Delta t, S_k^m, Y_j^m)\},$$

with transition probabilities which ensure that $(t, S_t, Y_t) \in \mathcal{T}$.

- In our examples we take $\dim(Y) = 1$ and two possible successor values for each S_k^m and Y_l^m .

Preferences

Utility for terminal wealth (with and without contingent claim) restricted to **class** \mathcal{H} of functions $f : \mathbb{R} \rightarrow \mathbb{R} \cup \{-\infty\}$ satisfying

- f is closed proper concave, so epigraph

$$\text{Epi}_f = \{(x, y) \mid y \leq f(x)\}$$

is a closed convex subset of \mathbb{R}^2 , and

- on its effective domain $E_f = \{x \in \mathbb{R} : f(x) > -\infty\}$, f is piecewise linear and the number of points where f is not differentiable is finite on E_f , and
- there exists an $\bar{x} \in \mathbb{R}$ such that $f(x)$ is a real constant for all $x \geq \bar{x}$.

Interior left- and righthand side derivatives exist and are monotone.

Preferences

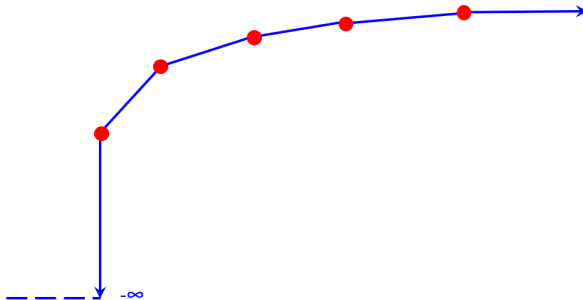


Figure: Example of a function in class \mathcal{H} .

Optimization Problem

For a given utility function $U \in \mathcal{H}$, we look for strategy ϕ maximizing expected utility of terminal wealth at $T = n\Delta t$:

$$\max_{\phi \in \Phi} \mathbb{E}[U(W_T^\phi)] \quad (1)$$

subject to

$$W_{t+\Delta t}^\phi = \phi_t(X_t) \frac{S_{t+\Delta t}}{S_t} + (W_t^\phi - \phi_t(X_t)) R(t) \quad (2)$$

where strategy ϕ for investment in risky asset can depend on state $X_t = (S_t, Y_t, W_t)$, R is deterministic risk-free rate, and $W_0^\phi = w_0$ the initial wealth.

Indifference pricing

Value function for problem without and with contingent claim paying $\Psi(X_T)$:

$$V_{t,S_t,Y_t}(W_t) = \max_{\phi_t, \phi_{t+\Delta t}, \dots, \phi_T} \mathbb{E}[U(W_T^\phi) \mid X_t]$$

$$\tilde{V}_{t,S_t,Y_t}(W_t) = \max_{\tilde{\phi}_t, \tilde{\phi}_{t+\Delta t}, \dots, \tilde{\phi}_T} \mathbb{E}[U(W_T^{\tilde{\phi}} - \Psi(X_T)) \mid X_t]$$

Selling price $\pi_\Psi(w_0)$ of claim Ψ must satisfy

$$V_{0,S_0,Y_0}(w_0) = \tilde{V}_{0,S_0,Y_0}(w_0 + \pi_\Psi(w_0))$$

Structure we exploit: for every possible value of (t, S_t, Y_t) , optimal strategy only depends on wealth, so we write

$$\phi_t(X_t) = \beta_{t,S_t,Y_t}(W_t).$$

Main Result

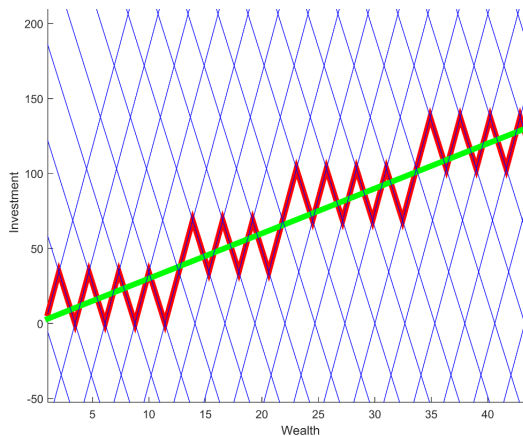
Invariance: dynamic programming principle maps \mathcal{H} on itself!

Theorem

Assume $V_{t,S,Y} \in \mathcal{H}$ for all $(t, S, Y) \in \mathcal{T}_{m+1}$. Then

- $V_{t,S,Y} \in \mathcal{H}$ for all $(t, S, Y) \in \mathcal{T}_m$.
- Functions $w \rightarrow \beta_{t,S,Y}(w)$ and $w \rightarrow V_{t,S,Y}(w)$ are continuous on their domain for all $(t, S, Y) \in \mathcal{T}_m$.
- Graph of optimal strategy $\{(w, \beta_{t,S,Y}(w)) : w \in \mathbb{R}\} \subset \mathbb{R}^2$ must lie on grid of 2 sets of parallel lines *that can be pre-computed*.

Optimal strategy is subset of known grid



Main Result

Theorem

Assume that $V_{t+\Delta t, uS, \star}$ and $V_{t+\Delta t, dS, \star}$ have singular values $x_1^u < x_2^u < \dots < x_{N_u}^u$ and $x_1^d, x_2^d < \dots < x_{N_d}^d$ respectively, and let

$$z_i^u = V_{t+\Delta t, uS, \star}'^-(x_i^u), \quad z_i^d = V_{t+\Delta t, dS, \star}'^-(x_i^d).$$

Then x_k (the singular values of $V_{t, S, Y}$ in reverse order), the optimal strategies $\beta_k = \beta_{t, S, Y}(x_k)$ and the left-hand side derivatives $z_k = V_{t, S, Y}'^-(x_k)$ satisfy, for $k \geq 1$,

$$\begin{aligned} x_k &= R^{-1}(qx_{i_k}^u + (1-q)x_{j_k}^d), & \beta_k &= (x_{i_k}^u - x_{j_k}^d)/(u-d), \\ z_u &= \frac{p}{q} z_{i_k}^u, & z_d &= \frac{1-p}{1-q} z_{j_k}^d, \\ z_k &= z_u \wedge z_d, & v_k &= v_{k-1} - z_{k-1}(x_k - x_{k-1}), \\ i_{k+1}^u &= i_k^u - \mathbf{1}_{\{z_k = z_u\}}, & i_{k+1}^d &= i_k^d - \mathbf{1}_{\{z_k = z_d\}}. \end{aligned}$$

Efficient Indifference Pricing

Consequence:

- Fast numerical algorithms: sequence of **binary choices**
- On finite state space in finite time we generate **exact solutions** for value functions, which must be in \mathcal{H}
- But increasing concave functions in \mathcal{H} also allow "deleting" of singular points which reduces computational cost for **a priori given error bound**: gives ϵ -close strategies.

This makes calculation of utility indifference prices relatively easy.

Approximation in \mathcal{H}

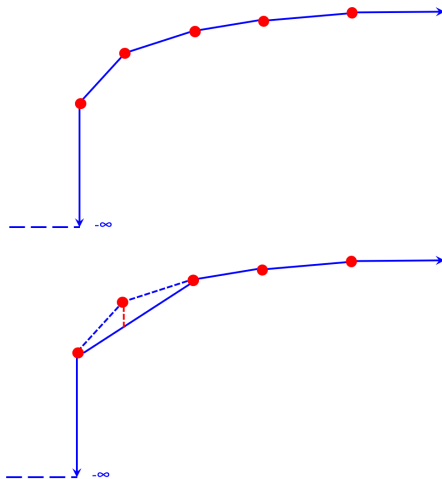


Figure: Example of a function in class \mathcal{H} and its approximation.

Convergence to viscosity solution

- To find approximations for investment strategies in continuous time problems we consider the HJB equation with (general) terminal utility \bar{U} and value function $\bar{V}_{t,S}(w)$:

$$\begin{aligned}\bar{V}_{T,S}(w) &= \bar{U}(w - \Phi(S)) \\ 0 &= \partial_t \bar{V} + \mu S \partial_S \bar{V} + \frac{1}{2} \sigma^2 S^2 \partial_{SS} \bar{V} \\ &\quad + \max_{\pi \in \mathbb{R}} \left[(r + \pi(\mu - r)) w \partial_w \bar{V} + \frac{1}{2} \sigma^2 w^2 \pi^2 \right]\end{aligned}$$

for a positive, bounded and globally Lipschitz continuous function Φ (Y is taken constant here).

- We assume that

$$(\forall w \geq \bar{w}) \quad 0 \leq \bar{U}(w) - \bar{u} \leq \bar{c}(w - \bar{w})^{1-\bar{\gamma}}$$

for appropriate constants \bar{u} , \bar{c} , \bar{w} , $\bar{\gamma}$, which ensures solutions exist.

Convergence to viscosity solution

We create sequence of approximations with $n \in \mathbb{N}^*$ equidistant timesteps, n^ν terminal singular points at distance $n^{-\zeta}$ with $\nu > \zeta > 0$, and denote solutions by $\bar{V}_{t,S}^n(w)$ for all $(t, S, w) \in \mathcal{T}^n \times \mathbb{R}$.

Theorem

If the HJB equation has a unique viscosity solution \bar{V} that is increasing and concave for $(t, S, w) \in \mathcal{Z} = [0, T] \times [0, \infty) \times [\bar{w}, \infty)$, then we have for all $(t, S, w) \in \mathcal{Z}$:

$$\lim_{\substack{n \rightarrow \infty \\ \mathcal{T}^n \times \mathbb{R} \ni (t_n, S_n, w_n) \rightarrow (t, S, w)}} \bar{V}_{t_n, S_n}^n(w_n) = \bar{V}_{t, S}(w).$$

Exponential Indifference pricing

Model of (Musielà & Zariphopoulou, 2004) in continuous time

$$\begin{aligned} dS_t &= \mu_S S_t dt + \sigma_S S_t dW_t^S, \\ dY_t &= \mu_Y Y_t dt + \sigma_Y Y_t dW_t^Y, \quad d\langle W^S, W^Y \rangle_t = \rho dt, \end{aligned}$$

with only S tradeable.

Indifference price for contingent claim $\Psi(Y_T)$ under preferences $U(x) = -e^{-\gamma x}$ can be shown to be

$$\pi^{\text{cont}} = \frac{\ln \mathbb{E}\left[e^{\gamma(1-\rho^2)\Psi(Y_T)} \frac{dQ}{dP} \right]}{\gamma(1-\rho^2)}, \quad \frac{dQ}{dP} = e^{-\frac{\mu}{\sigma} W_T^S - \frac{\mu^2}{2\sigma^2} T}.$$

Exponential Indifference pricing

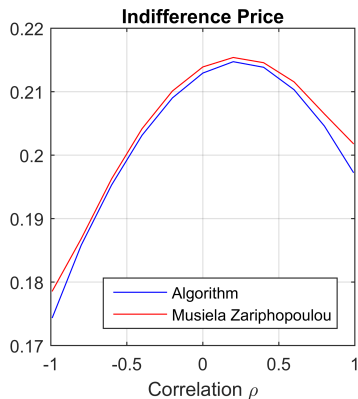
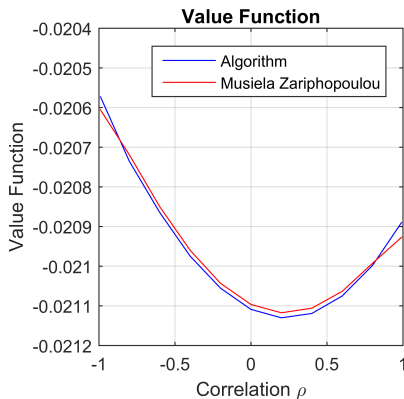


Figure: Parameters $S_0 = K = 5$, $\sigma = 10\%$, rest as before.

Optimal Strategies under Stochastic Volatility

Model (Heston, 1993) in continuous time:

$$\begin{aligned} dY_t &= \kappa(\theta - Y_t)dt + \omega\sqrt{Y_t}dW_t^S, \\ dS_t &= (r + \lambda Y_t)dt + \sqrt{Y_t}dW_t^Y, \quad d\langle W^S, W^Y \rangle_t = \rho dt, \end{aligned}$$

with λ the market price of volatility risk parameter.

Optimal strategy under CRRA with parameter γ is (Kraft, 2005)

$$\beta_{t,S_t,Y_t}^{\text{cont}}(w) = w \frac{(e^{a(T-t)} - 1)(\lambda + \gamma^{-1}(1 - \gamma)\rho\sigma\lambda^2)}{\gamma(e^{a(T-t)}(k + a) + a - k)}$$

$$k = \kappa - \frac{\rho\lambda\sigma}{1-\gamma^{-1}}, \quad c = \frac{\gamma}{\gamma + \rho^2(1-\gamma)}, \quad B = -\frac{\lambda^2(1-\gamma)}{2c\gamma}, \quad a = \sqrt{k^2 + 2B\sigma^2}.$$

Approximation in state space

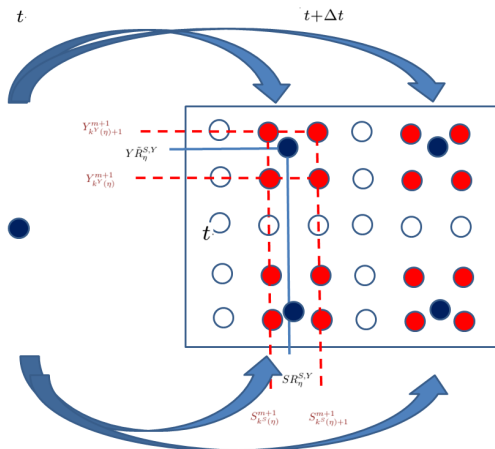


Figure: Approximation on grid implemented by "splitting" probabilities.

Nonlinear Strategies

SAHARA preferences (Chen, Pelsser & Vellekoop, 2011) :

$$U_{\gamma,\beta}(w) = \frac{1}{1-\gamma^2} \left(w + \sqrt{\beta^2 + w^2} \right)^{-\gamma} \left(w + \gamma \sqrt{\beta^2 + w^2} \right)$$

in standard Black-Scholes economy.

Optimal strategy:

$$\beta_{t,S_t}^{\text{cont}}(w) = \frac{\mu_S - r}{\gamma \sigma_S^2} \sqrt{w^2 + \beta^2 e^{-2(r - \frac{1}{2}((\mu_S - r)/(\gamma \sigma_S))^2)(T-t)}},$$

shows 'gambling for resurrection'.

Risk aversion is always positive but not monotone.

Approximations for continuous time problems

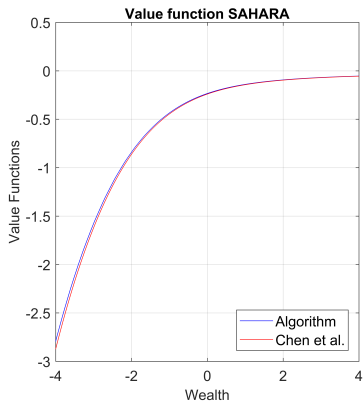
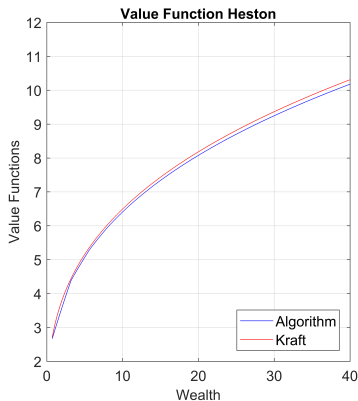



Figure: Parameters $r = 10\%$, $\sqrt{Y_0} = 25\%$, $\rho = 10\%$, $\omega = 39\%$, $\kappa = 1.15$, $\theta = 16\%$, $\lambda = \frac{1}{3}$, $\gamma = \frac{2}{3}$, $\alpha = 2$, $\beta = 2.66$.

Conclusions and Further Research

- Calculation of **exact** optimal investment strategies in discretized models is possible for ϵ -close preferences
- Good approximation of optimal value function does not necessitate smooth approximation of optimal investment strategy
- Algorithms are simple; mathematical work is in proving **continuity** of optimal strategy on the grid and **convergence** to viscosity solutions.

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