

AI in Actuarial Science - Two Years On

EAA e-Conference on Data Science & Data Ethics

29 June 2021

Ron Richman SA Taxi



Data - Ethics - Actuary

AI IN ACTUARIAL SCIENCE

Annals of Actuarial Science (2020), 1–23 doi:10.1017/S1748499520000238

REVIEW



Al in actuarial science – a review of recent advances – part 1

Ronald Richman¹⁰





AGENDA

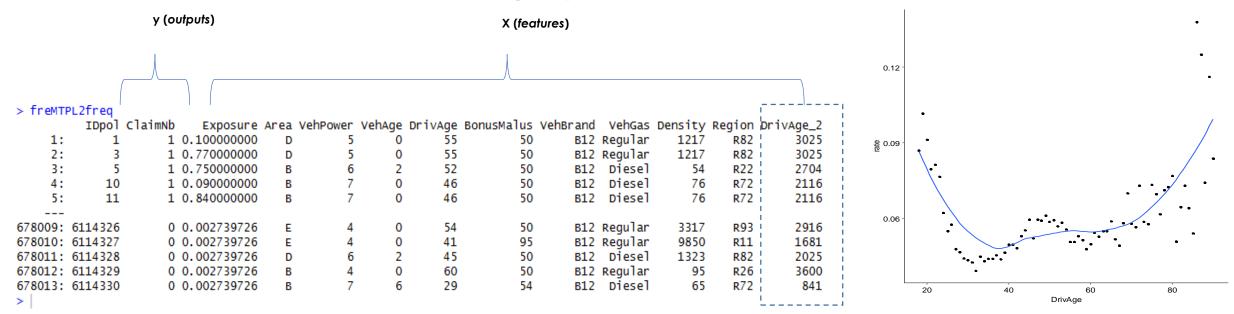
Deep Learning in 6 slides

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- Actuarial Examples of Representation Learning
- Advances in Deep Learning
- Applying Deep Learning in Actuarial Science
- Explaining Deep Learning models
- Uncertainty estimation
- Conclusions



- Supervised learning = application of machine learning to datasets that contain features and outputs with the goal of predicting the outputs from the features (Friedman, Hastie and Tibshirani 2009).
- Feature engineering Suppose we realize that Claims depends on Age²
 => enlarge feature space by adding Age² to data. Other options add interactions/basis functions e.g. splines



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- In many domains, traditional approach to designing actuarial/machine learning systems relies on human input for model specification/ feature engineering.
- Three arguments against traditional approach:

<u>Complexity</u> – which are the relevant features to extract/what is the correct model specification? Difficult with very high dimensional, unstructured data such as images or text. (Bengio 2009; Goodfellow, Bengio and Courville 2016)

<u>Expert knowledge</u> – requires suitable prior knowledge, which can take decades to build (and might not be transferable to a new domain) (LeCun, Bengio and Hinton 2015)

<u>Effort</u> – designing features is time consuming/tedious => limits scope and applicability (Bengio, Courville and Vincent 2013; Goodfellow, Bengio and Courville 2016)

 Complexity is not only due to unstructured data. Many difficult problems of model specification arise when performing actuarial/demographic tasks at a large scale



- Representation Learning = ML techniques where algorithms automatically design features that are optimal (in some sense) for a particular task
- Traditional examples are PCA (unsupervised) and PLS (supervised):

PCA produces features that summarize directions of greatest variance in feature matrix

PLS produces features that maximize covariance with response variable (Stone and Brooks 1990)

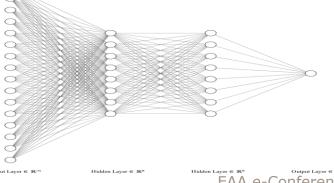
- Feature space then comprised of learned features which can be fed into ML/DL model
- BUT: Simple/naive RL approaches often fail when applied to high dimensional/very complex data



 Deep Learning = representation learning technique that automatically constructs hierarchies of complex features to represent abstract concepts

Features in lower layers composed of simpler features constructed at higher layers => complex concepts can be represented automatically

- Typical example of deep learning is feed-forward neural networks, which are multi-layered machine learning models, where each layer learns a new representation of the features.
- The principle: Provide raw data to the network and let it figure out what and how to learn.





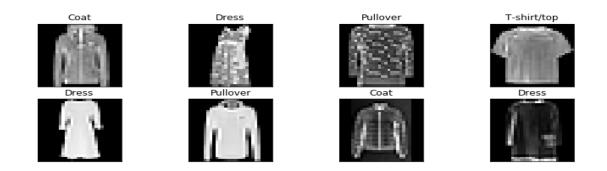
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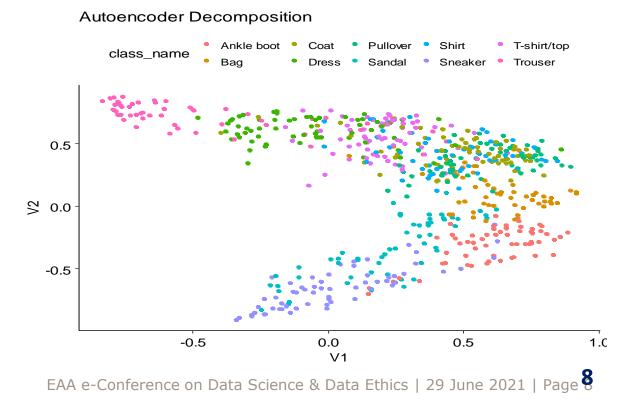
EXAMPLE: FASHION-MNIST

 Applied a deep autoencoder to the same data (trained in unsupervised manner)

Type of non-linear PCA

- Differences between classes shown
- Deep representation of data automatically captures meaningful differences between the images without (much) human input
- Automated feature/model specification









SPECIFYING MODELS – A NOTATION

Traditional Actuarial

$$M\left(X;T;\sum \beta_i f_i(xi);\Theta\right) = \hat{y}$$

• Linear model specification, for f_i identity (GLM), f_i spline function (GAM)

• β_i regression parameters

Machine Learning

$$M(X;T;S(A,\tilde{E});\Theta) = \hat{y}$$
 • Implicit Specification of the model \tilde{E} by a class of algorithms A

Deep Learning

• Representation Learning: Implicit Specification of functions
$$\tilde{T}$$
 to derive features X'
• Explicit use of loss function $L(y, \hat{y})$ to measure predictive accuracy

from Richman, von Rummell, & Wüthrich (2019)

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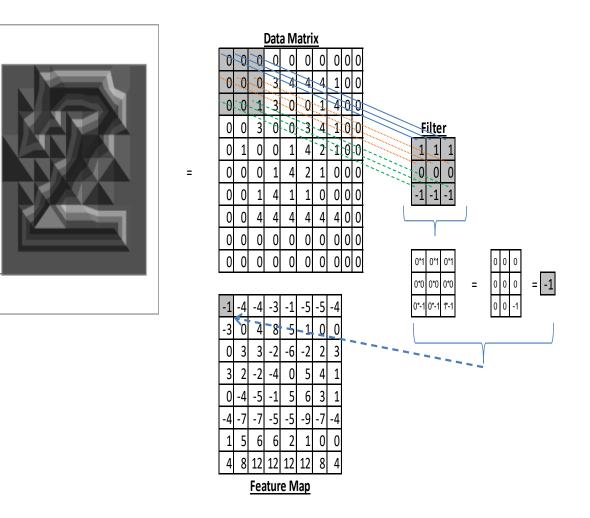
- When applied to tabular data, DL models perform representation learning on inputs:
 - Interaction terms
 - Non-linearities
- Paradigm of representation learning extends also to new types of data:
 - High dimensional
 - Unstructured
- Two recent examples mortality forecasting + telematics
- But first, a detour: Convolutional Neural Networks



Data - Ethics - Actuary Presentations

CONVOLUTIONAL NN - IMAGES

- Prior features in images are position invariant i.e. can recognize at any position within an image
- Also applies to audio/speech and text/time series data
- Convolutional network is locally connected and shares weights => expresses prior of position invariance
- Far fewer parameters than FCN
- Each neuron (i.e. feature map) in network derived by applying filter to input data
- Weights of filter learned when fitting network





- Forecast mortality rates = key inputs into demographic forecasting, life insurance and pensions models
- Foundational model for mortality forecasting is the Lee-Carter model (Lee and Carter 1992) (LC model)
- Mortality over time modeled using:

$$\log\left(u_{x,t}\right) = a_x + b_x k_t$$

- i.e. (log) mortality = average rate + rate of change . time index
- Relies on latent variables that must be estimated from data and then multiplied => use PCA to estimate the latent terms



- Can we derive features for mortality forecasting directly from past mortality rates using DL?
- In the LC model, we have the following regression function:

$$(t, x, i) \mapsto \log\left(u_{x,t}^{(i)}\right)$$

 $\log\left(u_{x,t}\right) = a_x + b_x k_t$

 Rather, can we map directly from observed mortality rates of many populations to a time feature:

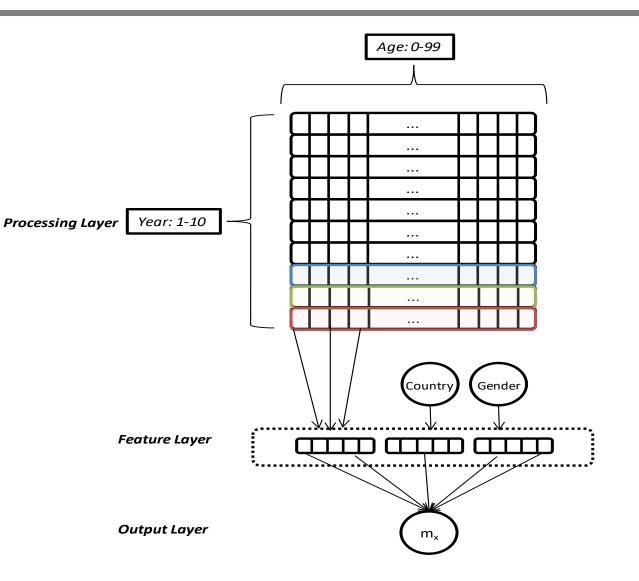
$$U^{(i)} \mapsto k_t^{(i)} \in \mathbb{R}^q$$

Addressed in Perla, Richman, Scognamiglio and Wüthrich (2020)



LCCONV - MODEL STRUCTURE

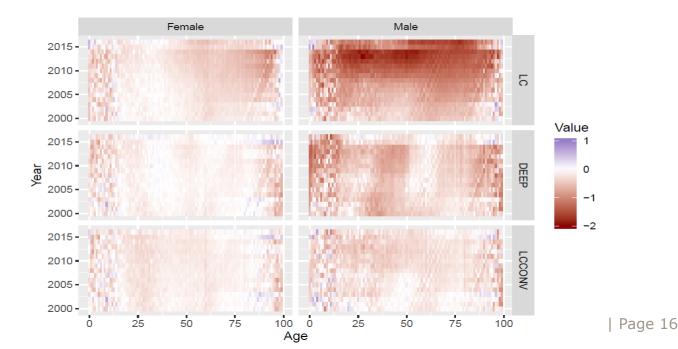
- Similar to LC model...
- … however, time variable replaced with outputs of a NN processing layer
- Best performance achieved with no non-linearities in the model
- Since features are used immediately for prediction, can be interpreted as an extended LC model:
- $\sigma^{-1}\left(\widehat{y}_{x,t_0+T+1}^{(r,g)}\right) = w_{x,0} + \left\langle W_x^{\mathcal{R}}, z_{\mathcal{R}}(r) \right\rangle + \left\langle W_x^{\mathcal{G}}, z_{\mathcal{G}}(g) \right\rangle + \left\langle W_x^f, z_f(U_{t_0}^{(i)}) \right\rangle$
 - First terms equivalent to ax
 - Last term equivalent to bx.kt





- european actuarial academy
 - The CNN model (LCCONV) achieves better performance versus the LC model on 75/76 populations in the HMD
 - Unadjusted model also generalized well – beat LC on 101/102 populations in the USMD
 - LCCONV beats the LCNN model in an extra 8 populations and achieves a substantially lower out-of-sample MSE
 - Residual plot shows that model is substantially better for males, whereas the performance is similar for females

model	$test_loss$	ensemble MSE	# populations
LCCONV	2.27	2.24	75/76
$LCCONV_{tanh}$	2.62	2.58	61/76
LCCONV_relu	3.26	3.10	57/76
LCLSTM1	2.86	2.54	69/76
$LCLSTM1_{tanh}$	3.32	3.03	58/76
$LCLSTM1_relu$	3.33	3.25	52/76
LCLSTM2	2.43	2.32	74/76
$LCLSTM2_{tanh}$	2.36	2.27	75/76
$LCLSTM2_relu$	3.44	3.11	56/76
DEEP	2.83	2.53	67/76



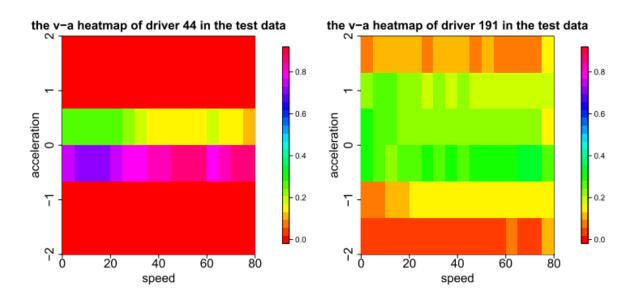


- Non-life pricing often performed using GLMs
- Traditional covariates relate to *policyholder, driver and* vehicle characteristics
- Recently enhanced through deriving features from telematics data
- Features of telematics data:
 - High dimensional
 - Sampled at high frequency
 - Incorporate physical measurements (location, seed, acceleration)
- Simple approaches include considering number/rate of unwanted events (see Guillen, Nielsen, & Pérez-Marín (2021))
- Other approaches summarize data in feature matrices for further analysis





- Velocity-Acceleration heatmaps due to Wüthrich (2017)
- Form 2S density plot of velocity and acceleration based on telematics data



- Can be analyzed using traditional methods e.g. k-means or PCA
- Recent work (Gao, Wang, & Wüthrich, 2021) analyzes heatmaps directly using FCN and CNN



- Combine traditional actuarial covariates with telematics data using boosting:
 - First model GLM using actuarial covariates
 - Second model once fit, add neural network component to improve calibrations

 $Y_i \stackrel{\text{ind.}}{\sim} \text{Poisson}(e_i \widehat{\lambda}(\mathbf{x}_i) \rho^{\text{dnn}}(\mathbf{Z}_i)),$

 $Y_i \stackrel{\text{ind.}}{\sim} \text{Poisson}(e_i \hat{\lambda}(\mathbf{x}_i) \rho^{\text{cnn}}(\mathbf{Z}_i)),$

 Results show that adding covariates learned from heatmaps decreases test set error by ~10%:

Error	Homogeneous (2.6)	GLM (2.4)	dnn Listing 1	cnn Listing 2	dnn + glm (4.1)	cnn + glm (4.2)
Learning error	1.0717	1.0205	1.0376	1.0415	0.9982	0.9992
Test error	1.1703	1.1230	1.1035	1.1075	1.0655	1.0690
Reduction in test error		0.0473	0.0668	0.0628	0.1048	0.1013

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- Most state of the art deep learning results use specialized architectures:
 - Convolutional neural networks
 - Recurrent neural networks
 - Embeddings
- Older ideas enhanced by modern approach to neural networks:
 - More powerful computing (GPUs/TPUs)
 - Larger datasets (ImageNet/NLP corpora)
 - Advances in methodology: dropout, batchnorm, ReLu
- Led to state of the art advances on problems across many areas of machine learning:
 - Computer vision
 - Natural language processing
 - Speech recognition



- Newer approach proposed in 2017 relies on *attention mechanisms*
- One of most cited papers in machine learning (>23k):

Attention Is All You Need

Ashish Vaswani* Noam Shazeer* Niki Parmar* Jakob Uszkoreit* Google Research Google Brain Google Brain Google Research avaswani@google.com noam@google.com nikip@google.com usz@google.com Aidan N. Gomez* † Łukasz Kaiser* Llion Jones* Google Research University of Toronto Google Brain llion@google.com aidan@cs.toronto.edu lukaszkaiser@google.com

> Illia Polosukhin*[‡] illia.polosukhin@gmail.com

- Proposed in context of machine translation
- Extended to other NLP tasks, computer vision and more recently, tabular data







- Most actuarial models rely on fixed relationship between covariates (features) and outcomes; more flexible models (varying coefficient models) in statistical literature allow coefficients of models to vary with time (or other covariates)
- Generalized approach to allow for varying relationships between covariates and outcomes is *attention* (example from Xu et al., 2015)



A woman is throwing a frisbee in a park.



A dog is standing on a hardwood floor.



A stop sign is on a road with a mountain in the background.



A little girl sitting on a bed with a teddy bear.

A group of people sitting on a boat in the water.



A giraffe standing in a forest with trees in the background.



 When building models, relationships between covariates and outcomes may depend on *context*.

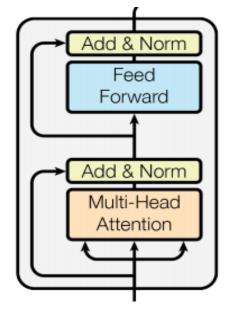
Famous example in non-life insurance – young drivers and male drivers often have increased frequency, but *young male* drivers may experience even higher frequency => context allow for via interaction effect

- Automated method for building context into models: self-attention i.e. apply attention over inputs; sequence example (Cheng, Dong, & Lapata, 2016)
 - The FBI is chasing a criminal on the run. The FBI is chasing a criminal on the run. The FBI is chasing a criminal on the run. FBI is chasing a criminal on the run. The FBI is chasing a criminal on the run. The FBI is chasing a criminal on the run. The chasing a criminal on the run. FBI is The FBI is chasing a criminal on the run. The FBI is chasing a criminal on the run. The





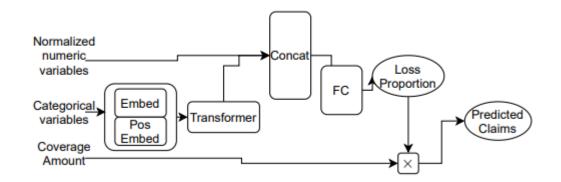
- Transformer models apply self-attention to augment model covariates depending on context (Vaswani et al., 2017):
 - 1. Inputs fed to multiple self-attention components
 - 2. Attention results added to original input and then centred/scaled
 - 3. Then fed into feed forward network
 - 4. Attention and feedforward results added and then centred/scaled





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- Transformer model recently applied in Kuo & Richman (2021) to model flood loss severity
- Model tries to predict damage ratio (proportion of exposure damaged) using several continuous and categorical covariates



Best results achieved using Transformer based model

Model	RMSE	MAE
Model 4: MLP with multidimensional embeddings	60,973	37,574
Model 5: Simple Attention	60,601	36,739
Model 6: TabNet	62,938	38,386
Model 7: TabTransformer	59,900	36,343
Linear regression, predictions capped below at 0.01	60,879	38,431





EMBEDDING LAYER – CATEGORICAL DATA

- One hot encoding expresses the prior that categories are orthogonal => similar observations not categorized into groups
- Embedding layer prior related categories should cluster together
- Learns dense vector transformation of sparse input vectors and clusters similar categories together

	Actuary	Accountant	Quan	t	Statistician	Economist	Underwriter
Actuary	1		0	0	0	0	0
Accountant	0		1	0	0	0	0
Quant	0		0	1	0	0	0
Statistician	0		0	0	1	0	0
Economist	0		0	0	0	1	0
Underwriter	0		0	0	0	0	1
		Finance	Math		Stastistics	Liabilities	
	Actuary	0.	.5	0.25	0.5	0.5	
	Accountant	0.	.5	0	0	0	
	Quant	0.7	75	0.25	0.25	0	
	Statistician		0	0.5	0.85	0	
	Economist	0.	.5	0.25	0.5	0	
	Underwriter		0	0.1	0.05	0.75	



- Embeddings for categorical covariates + Self-attention for context = contextual embeddings
- Example shown for flood zone embeddings (left) colored according to house design variable (crawl space)

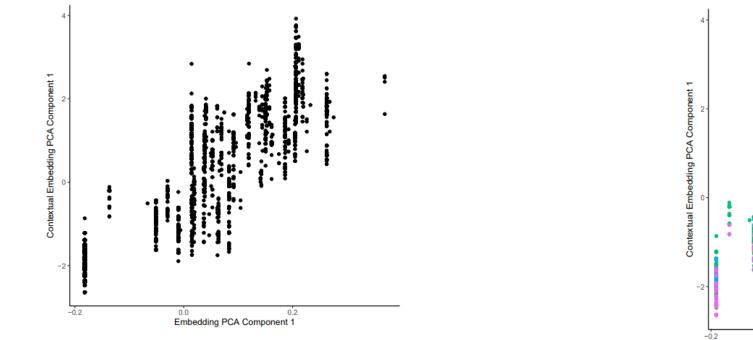


Figure 8: Embedding versus Contextual Embedding, Flood Zone, first PCA components

0.2

0.0

Embedding PCA Component 1

basement enclosure crawlspace

Finished Basement/Enclosure

Subgrade Crawlspace
 Unfinished Basement/Enclosure

Crawlspace

None



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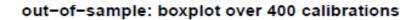
- Neural network training incorporates random processes
- Fundamental source of randomness: random initialization of starting parameters and not training to convergence (early stopping)
- Other sources:

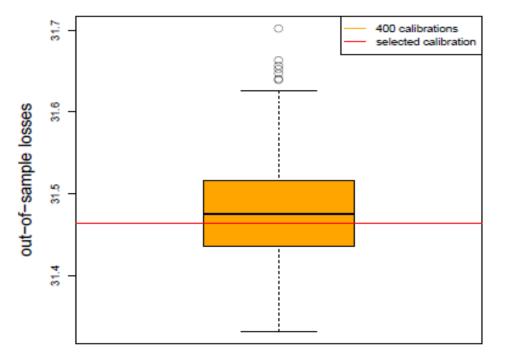
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- random ordering of batches fed to network
- dropout = randomly switch off parts of the network to regularize
- within vision models random data augmentation
- Leads to robust models on the one hand...
- ... and models that depend on the random seed (i.e. are not reproducible) on the other

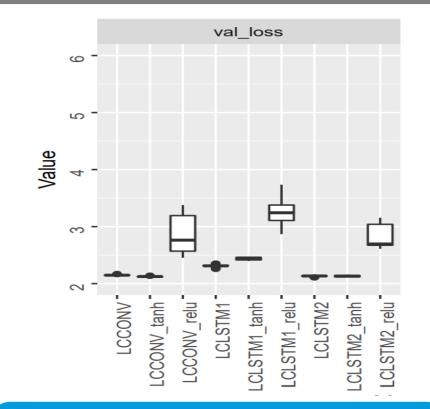








Neural networks fit to French MTPL dataset Richman and Wüthrich (2020)



Neural networks fit to HMD dataset Perla, Richman, Scognamiglio and Wüthrich (2020)

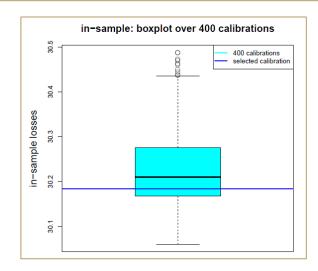


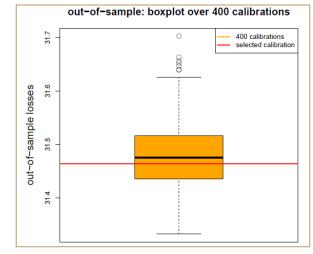
- Aggregating is a statistical technique that helps to reduce noise and uncertainty in predictors and is justified theoretically using the law of large numbers.
- An i.i.d. sequence of predictors is not always available thus, Breiman (1996) combined bootstrapping and aggregating, called bagging.
- Combine networks and aggregating to receive the *nagging* predictor i.e. use multiple network predictors for aggregation (Richman & Wüthrich, 2020)
- => Same situation as Breiman (1996) after having received the bootstrap samples
- Leads to more stable results and enhanced predictive performance.



• Applied nagging to French MTPL data and fit 400 networks

	In-Sample Loss on ${\cal D}$	Out-of-Sample Loss on ${\mathcal T}$
(a) homogeneous model	32.935	33.861
(b) generalized linear model	31.267	32.171
(c) boosting regression model	30.132	31.468
(d) network regression model (seed $j = 1$)	30.184	31.464
(e) average over 400 network calibrations (f) nagging predictor for $M = 400$	30.230 (0.089) 30.060	31.480 (0.061) 31.272

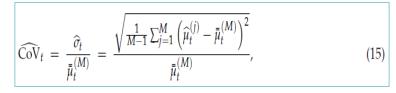




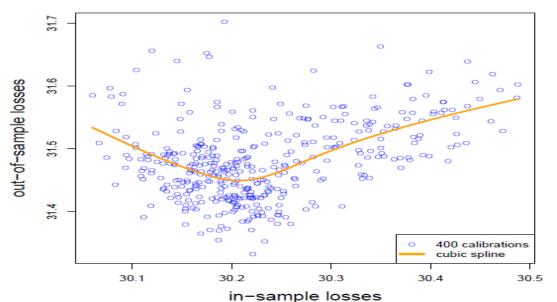
NAGGING RESULTS (2)



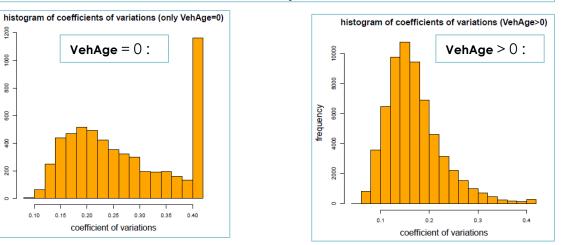
- Shape of training losses versus testing losses => don't underfit or overfit the training data
- Diagnostic for model convergence for individual observations = CoV of predictions



- Allows for identification of observations that are harder to fit
- Within French MTPL data, observations with vehicle age 0 appear to have different properties



scatter plot of in-sample and out-of-sample losses



frequency

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SOURCES OF RANDOMNESS

- How is stability of neural networks affected by different choices of architecture, regularization and training procedure?
- Investigated in Richman (2021) in context of mortality forecasting
- Following components tested:
 - dimension of the intermediate layers
 - dimension of the embedding and convolutional layers
 - activation function of the intermediate layers
 - application of batch normalization
 - depth of the network
 - drop-out rates
 - size of batches
 - learning rate, restarts and optimizer

	Model	type	Average MSE	Median MSE	Best Performance
1	LC_SVD	National	5.55	2.48	5
2	LC_SVD	Sub-National	22.08	1.48	20
3	DEEP	National	2.38	1.31	71
4	DEEP	Sub-National	20.49	0.78	216

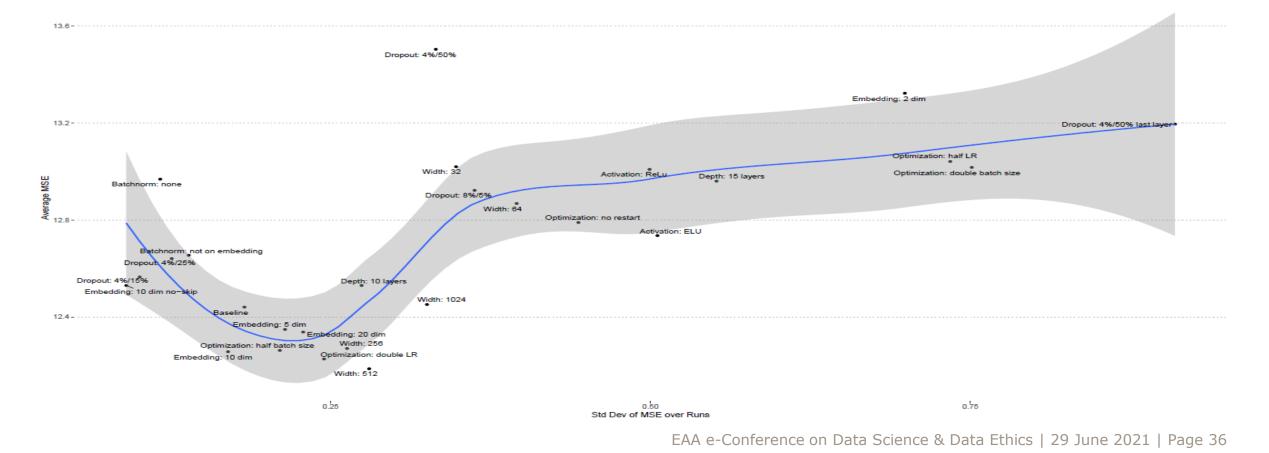
	Description	Average MSE	Std Dev of MSE
1	Baseline	12.55	0.18
2	Width: 256	12.47	0.26
3	Width: 512	12.43	0.28
4	Width: 1024	12.67	0.33
5	Width: 32	13.16	0.35
6	Width: 64	13.01	0.40

	Description	MSE	Best Performance over Populations
1	Width: 512	12.18	296
2	Width: 256	12.27	288
3	Baseline	12.44	287
4	Width: 1024	12.45	279
5	Width: 64	12.87	247
6	Width: 32	13.02	235

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 Plot shows relationship between randomness of outcomes and nagging predictor performance => some variability is good, but too little/too much is bad





- One view on non-life pricing = finding good base rate predictions for portfolio + set of relativities to allow pricing to vary with risk
- If using GLM => portfolio base rates reproduced by model i.e. the 'balance property' is preserved
- Neural networks and other ML algorithms do not have this property so must correct for this, see Wüthrich (2019) and Denuit, Charpentier, & Trufin (2021)
- Within life insurance, experience analysis assesses bias of predictions using AvE metrics (and only more rarely do we consider predictive accuracy)
- See Rossouw & Richman (2019) for discussion of bias regularization in a life reinsurance context



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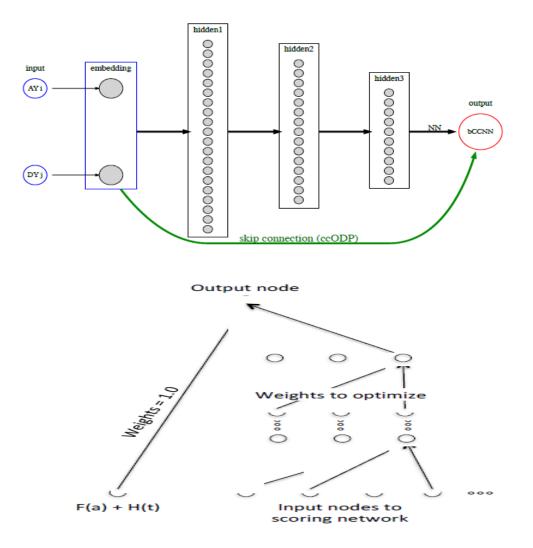
Simulatability	Being able to comprehend the model as a whole	 Develop expert knowledge on model architecture and heuristics to assess models Issue pertains to some traditional models as well 							
Decomposability	All components of the model can be inspected and make sense	 Inspect learned representations in last layer of the model Manual intervention and inclusion of prior knowledge is more difficult 							
Algorithmic Transparency	Transparency of the learning algorithm and corresponding techniques	 Many techniques to mitigate risks of instability and consistency of DLM still to be developed Ensembling many models and use of toy models to test outcomes of DLM 							
Increased exposure to model risk for ML/DL models and additional controls required									
1: Lipton (2016) defines framework for model interpretability to assess two basic questions: Transparency or "How does the model work?" and Post-hoc Interpretability or "What else can the model tell me?"									





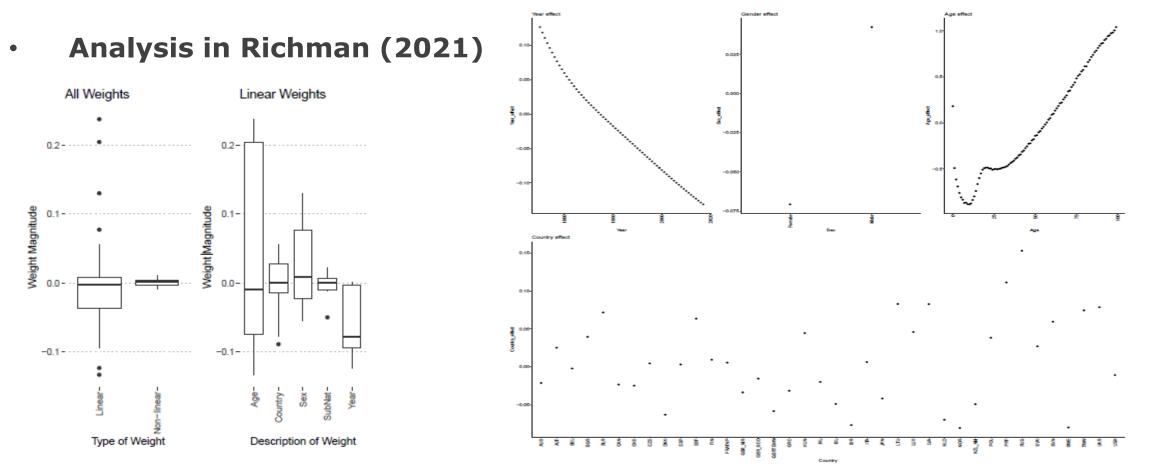
COMBINED ACTUARIAL NEURAL NET (CANN)

- Combine a traditional actuarial model together with a neural net (Wüthrich and Merz 2018). Implemented so far for pricing and reserving (Gabrielli 2019; Gabrielli, Richman and Wuthrich 2018)
 - Traditional model (calibrated with MLE) directly connected with output of network using skip connection
 - Model output then enhanced by model structure learned by neural net to explain residuals
 - Easy to interpret (and fast to calibrate)
- Shifts the interpretability problem delta from GLM
- See Breeden and Leonova (2019) who use a similar proposal to incorporate prior economic information into a credit model





 Here we show linear effects from the model and weight magnitude of nonlinear component

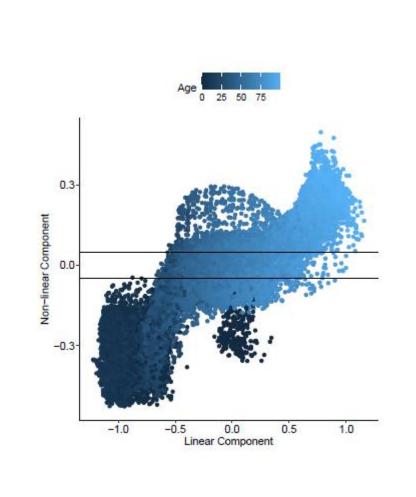


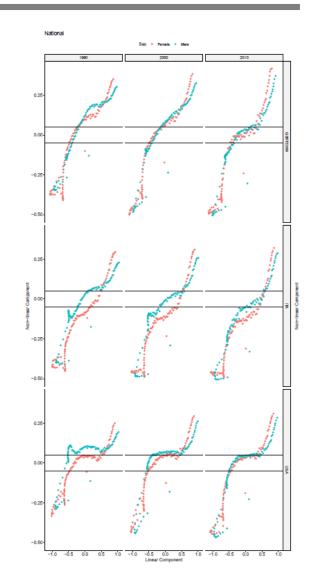


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INVESTIGATING NETWORK NON-LINEARITIES

- Use the CANN model to highlight major differences from predictions of traditional model i.e. isolate the network output => model diagnostic
- Complex relationship between linear and non-linear component as function of Year, Country, Gender and Age variables









- Hard to disentangle relationship between inputs and outputs in a deep learning model =>
- Can we use the flexibility/function approximation capability of neural networks to fit specific variable combinations?
- Explainable neural networks (XNNs) and Neural Additive Models (NAM) of Vaughan et al. (2018) and Agarwal et al. (2020)

$$\hat{y}_i = \mu + \gamma_1 f_1(x_{i,1}) + \gamma_2 f_2(x_{i,2}) + \dots + \gamma_P f_P(x_{i,P})$$

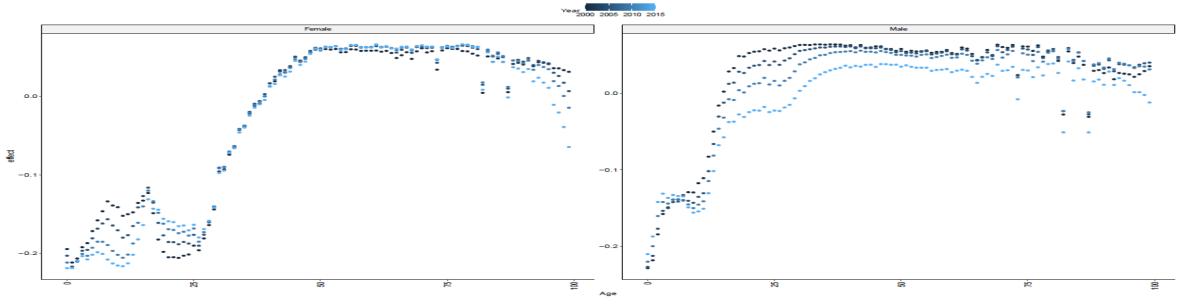
- Combined Actuarial eXplainable Neural Network (CAXNN)
- See Richman (2021) for extensions of XNNs and applications within mortality forecasting



• CAXNN Model reproduces nagging predictor in an explainable manner

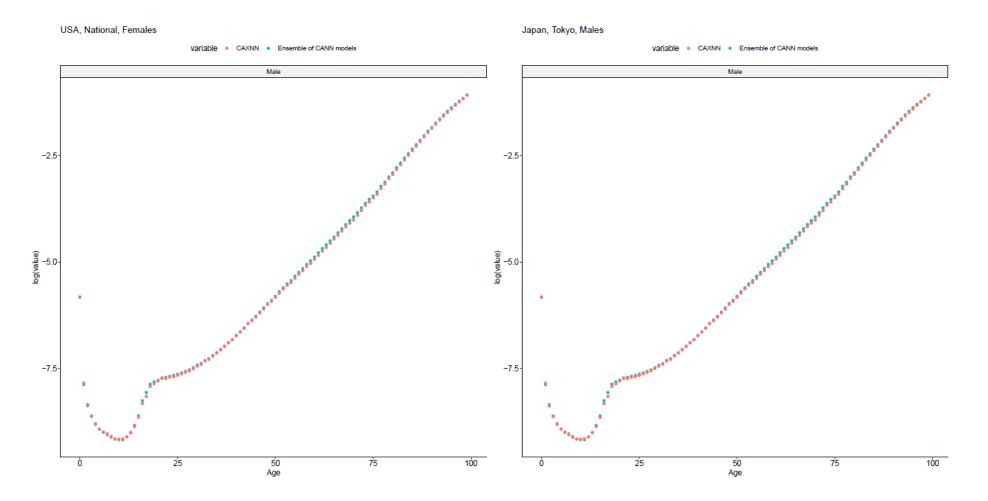
	Model	type	Average MSE	Median MSE	Best Performance		Model	type	Average MSE	Median MSE	Best Performance
1	LC_SVD	National	5.55	2.48	35	1	LC_SVD	National	5.55	2.48	9
2	LC_SVD	Sub-National	22.08	1.48	43	2	LC_SVD	Sub-National	22.08	1.48	21
3	Linear	National	4.28	3.07	41	3	DEEP	National	2.67	1.46	67
4	Linear	Sub-National	20.94	0.95	193	4	DEEP	Sub-National	20.60	0.90	215

Year/Age/Sex effect





CAXNN Model reproduces nagging predictor in an explainable manner





AGENDA

• Deep Learning in 6 slides

Data - Ethics - Actuary

- Actuarial Examples of Representation Learning
- Advances in Deep Learning
- Applying Deep Learning in Actuarial Science
- Explaining Deep Learning models
- Uncertainty estimation
- Conclusions



- Ability to quantify extent of uncertainty in predictions is key to many actuarial tasks; however, focus of deep learning literature is on best estimate
- Several approaches proposed in DL literature:
 - Use of dropout as an approximation of model uncertainty (Gal 2016; Kendall and Gal 2017)
 - Quantile regression to derive prediction bounds (Smyl 2018)
 - Use neural networks for GAMLSS regression
- Not immediately obvious how to reconcile to traditional actuarial framework (often relies on bootstrapping)
- Seemingly, framework of Kendall and Gal (2017) for computer vision correlates with traditional actuarial understanding (model and parameter risk = epistemic uncertainty; process risk = aleatoric uncertainty)





- Gabrielli, Richman and Wüthrich (2019) apply bootstrap to the multi-LoB ODP NN model – found that decreased bias almost to zero but increased RMSEP versus separate ODP models
 - Bootstrap only feasible due to fast calibration of CANN models
- More recently, Schnürch & Korn (2021) apply bootstrapping to neural network-based mortality forecasting models and find intervals thus produced are well calibrated for some of the models
- Also see Marino & Levantesi (2020)



- In Richman (2021) we have applied methods from the ML/DL literature
- Quantile regression (using pinball loss) shown to produce very well calibrated prediction intervals in M4 Forecasting competition

$$L(y_i, \hat{y}_i, \tau) = \begin{cases} \tau \ (y_i - \hat{y}_i) & \text{if } y_i - \hat{y}_i \ge 0\\ (\tau - 1) \ (y_i - \hat{y}_i) & \text{if } y_i - \hat{y}_i < 0 \end{cases},$$

 Deep ensembles use heteroskedastic Gaussian regression and multiple training runs to derive prediction intervals (Lakshminarayanan *et al.* 2017):

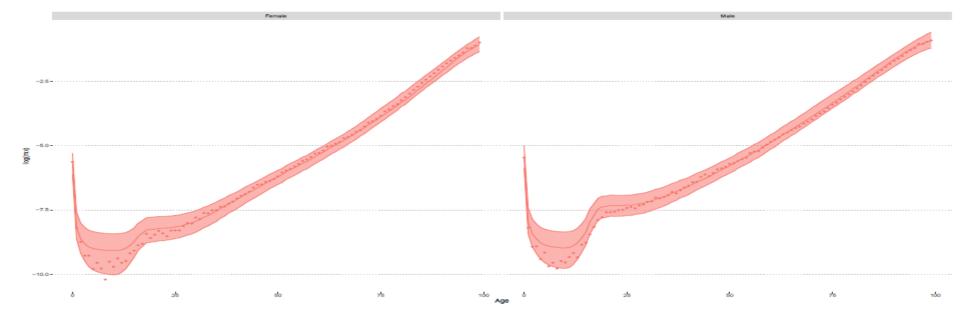
$$L(\hat{y}_i) = \frac{(y_i - \hat{y}_i)^2}{\sigma_i^2} + \frac{\log(\sigma_i^2)}{2}.$$

• Note that DE have Bayesian interpretation (Wilson & Izmailov, 2020)



Achieve excellent empirical coverage out of sample i.e. well calibrated

	Description	Data Exceeding 97.5%	Data Exceeding 2.5%	Coverage	Delta
1	Pinball Loss, ReLu branches	0.022	0.026	0.048	0.002
2	Pinball Loss, tanh branches	0.021	0.026	0.048	0.002
3	Deep Ensemble	0.026	0.029	0.055	0.005
4	Deep Ensemble, ReLu branches	0.012	0.030	0.043	0.007
5	Pinball Loss	0.017	0.025	0.042	0.008
6	Deep Ensemble, tanh branches	0.014	0.027	0.041	0.009



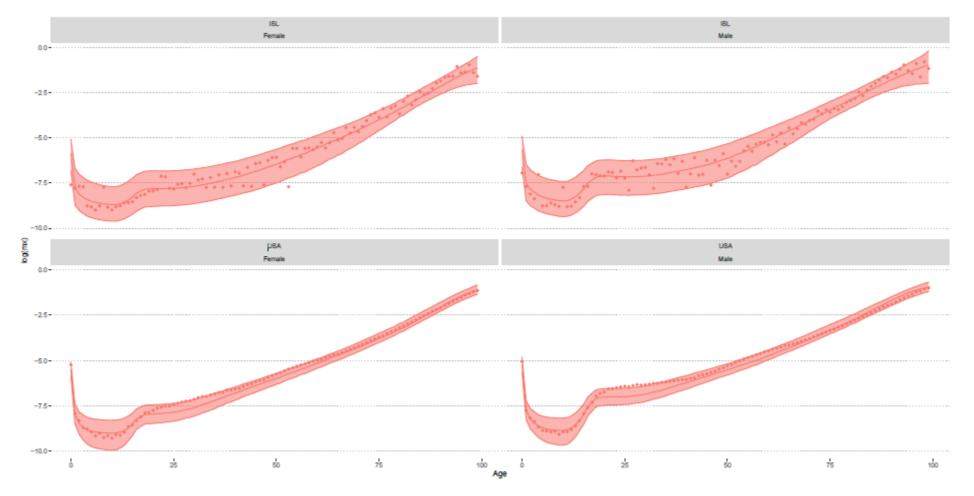
Perhaps too narrow due to parameter error that was not evaluated

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QUANTILE REGRESSION – INTUITIVE RESULTS

Results accord with intuition





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- **Outside of actuarial science:**
 - Applying transformers for computer vision (Dosovitskiy et al. 2020)
 - The "self-supervised revolution" (LeCun & Misra, 2021)
 - DL versus GBDT (Kadra et al. 2021) ullet
- Within actuarial science:
 - Last layer analysis (Richman, von Rummell, & Wüthrich, 2019) \bullet
 - Marginal attribution by condition on quantiles (Merz, Richman, ulletTsanakas, & Wüthrich, 2021)
 - Discrimination free pricing (Lindholm, Richman, Tsanakas, & Wüthrich, \bullet 2020)



- Deep learning:
 - opens new possibilities for actuarial modelling by solving difficult model specification problems, especially those involving large scale modelling problems
 - allows new types of high frequency data to be analysed
 - enhances the predictive power of models built by actuaries
- Recent work has expanded the toolkit of actuarial data science by:
 - applying representation learning directly on novel data sources
 - applying new DL methods
 - showing how DL models can be made explainable/interpretable
- More work is needed on uncertainty estimation





Reading club to go through new book by Mario Wüthrich and Michael Merz
 https://papers.ssrn.com/sol3/papers.cfm?abstract_id=3822407

STATISTICAL FOUNDATIONS OF ACTUARIAL LEARNING AND ITS APPLICATIONS

> Mario V. Wüthrich RiskLab Switzerland Department of Mathematics ETH Zurich

MICHAEL MERZ FACULTY OF BUSINESS ADMINISTRATION HBS – HAMBURG BUSINESS SCHOOL UNIVERSITY OF HAMBURG

Contact me if this is of interest





THANK YOU

- Mario Wüthrich
- Andreas Tsanakas
- Michael Merz
- Mathias Lindholm
- Kevin Kuo
- Nicolai von Rummell
- Louis Rossouw





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Ron is an experienced actuary and risk manager, currently Managing Head of Insurance Actuarial at SA Taxi. Before this he was an Associate Director at QED Actuaries and Consultants, Africa's largest independent actuarial consulting firm, where he was responsible for client work on life and general insurance clients and performing research into applications of machine learning and AI to actuarial and insurance topics. Prior to this, he led the **Enterprise Risk Management and Actuarial Functions** for the AIG group within Africa.

Ron is a Fellow of the Institute and Faculty of Actuaries (IFoA) and the Actuarial Society of South Africa (ASSA), holds practicing certificates in Short Term Insurance and Life Insurance from ASSA, and a Masters of Philosophy in Actuarial Science, with distinction, from the University of Cape Town.

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