



## Compression of Life Insurance Portfolios

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## Actuarial projections in life insurance

- ▶ project a life insurance company's assets and liabilities into the future
- ▶ over a specified time horizon and a set of scenarios
- ▶ in order to assess the company's future corporate performance and
- ▶ to identify potential risks
- ▶ required e.g. for ALM, Solvency II, a company's internal planning process

## Complexity of actuarial projections

- ▶ long time horizon and many time steps
  - ▶ large number of scenarios, e.g. financial market
  - ▶ simultaneous projection and adjustment of assets and liabilities
  - ▶ dynamic management rules
  - ▶ nested simulations for valuing embedded options and guarantees in insurance contracts
  - ▶ for a liability portfolio of millions of policies
- ⇒ causes an enormous computational complexity requiring massive runtime and storage requirements

## Possible solutions

- ▶ increase computational power of hardware and software
- ▶ estimate central quantities with proxy functions w.r.t underlying risk factors
- ▶ reduce number of scenarios
- ▶ replace liabilities by a replicating portfolio of standard assets
- ▶ use replicated stratified sampling for sensitivity analysis [7]
- ▶ compress the liabilities, i.e. select a small number of model points replacing the original liability portfolio

## Mathematical model

- ▶ insurance contract  $C_i = \{c_j^{(i)}, j = 1, 2, \dots\}$
- ▶ portfolio of feasible contracts  $P = \{C_1, \dots, C_n\} \in \mathcal{P}$ ,  
 $n \in \mathbb{N}$
- ▶ set of quantities  $\mathcal{Q}$
- ▶ time horizon  $\mathcal{T}$
- ▶ set of scenarios  $\mathcal{S} = \{s : \mathcal{T} \rightarrow \Omega\}$
- ▶ actuarial projection  $f_P : \mathcal{Q} \times \mathcal{T} \times \mathcal{S} \rightarrow \mathbb{R}$ ,  
 $f_P(j, t, s) = y_{jts}^{(P)}$
- ▶ compression  $c : \mathcal{P} \rightarrow \mathcal{P}, P \mapsto P^{MP}$

Two main requirements towards compressed portfolio:

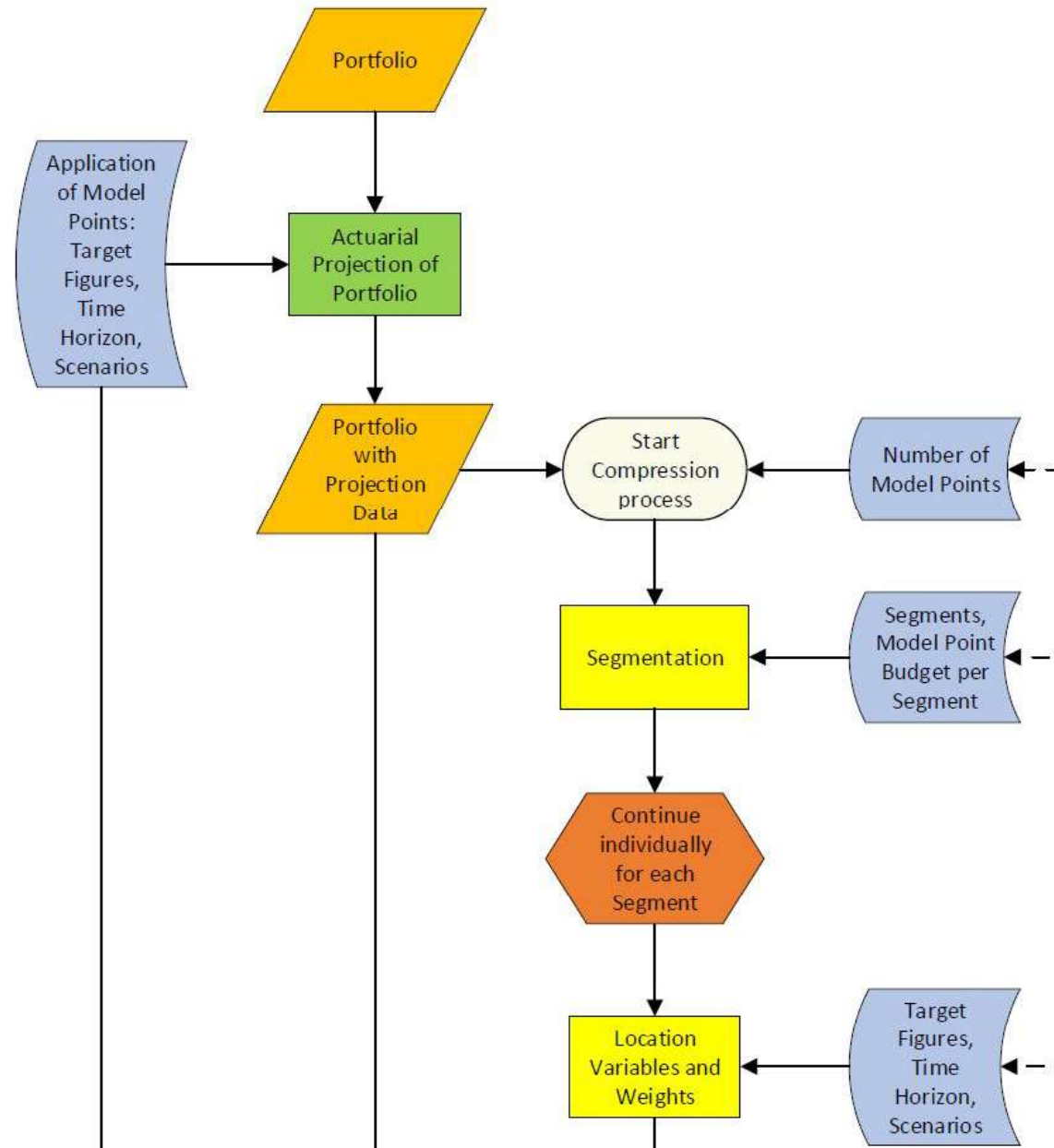
- ▶ include significantly less policies than the original portfolio  $P$ :  $|P^{MP}| \leq m$
- ▶ accurately represent the portfolio  $P$  in actuarial projections:  $d_{Q,T,S}(P, P^{MP}) \rightarrow \min$

Optimization problem:

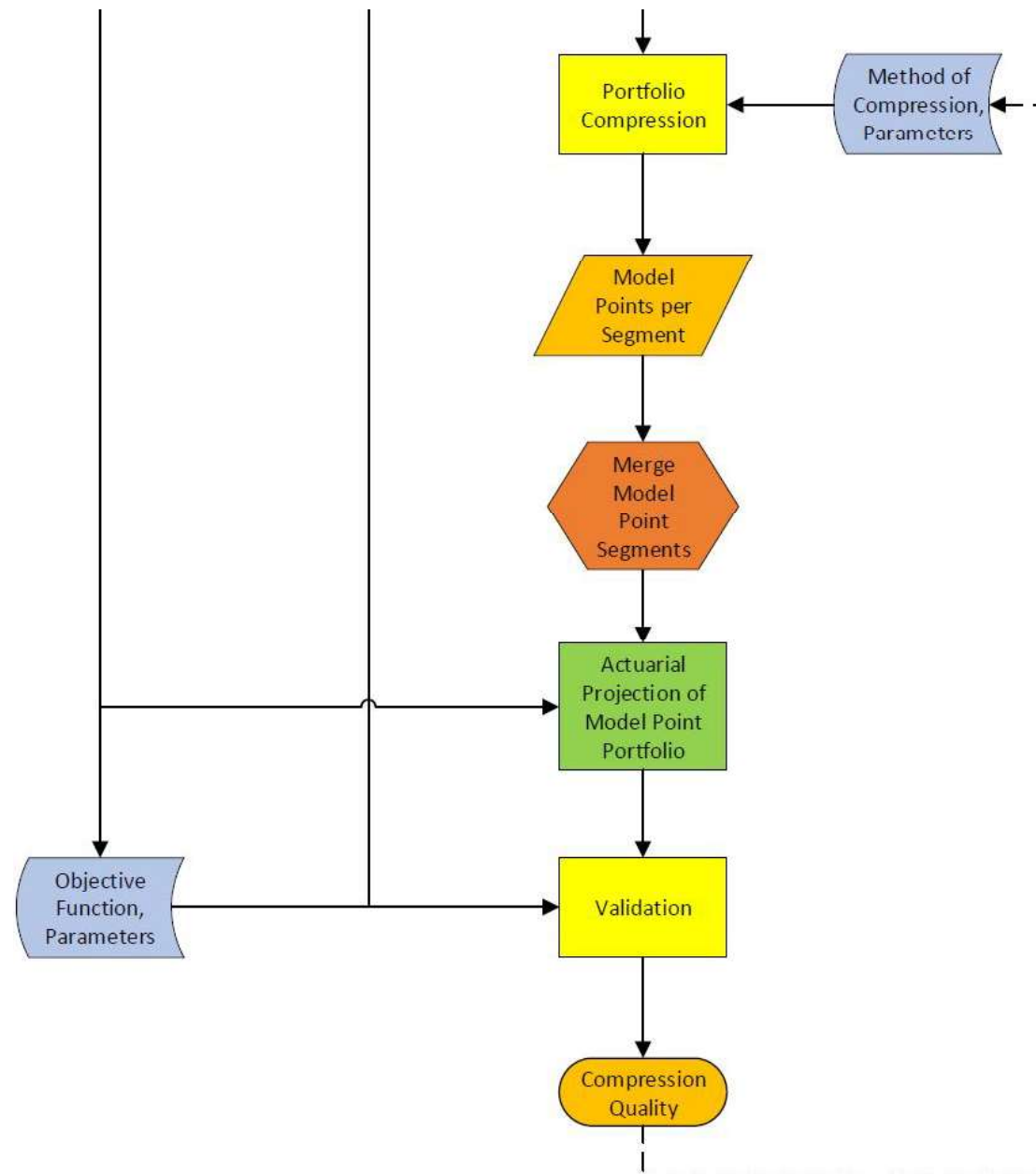
$$(OP) \begin{cases} d_{Q,T,S}(P, P^{MP}) \rightarrow \min, \\ e_{Q,T,S}(P, P^{MP}) \leq \mathbf{0}, \\ |P^{MP}| \leq m, \end{cases}$$

$\Rightarrow$  How to set up  $d_{Q,T,S}$ ?

# Process model







## Standard actuarial grouping methods

- ▶ split portfolio manually into segments based on contract features
- ▶ represent each segment by a single model point by
- ▶ aggregating contract features within each segment, e.g. by summation, averaging

### Shortcomings:

- ▶ insufficient compression ratios [3]
- ▶ number of model points cannot be set in advance
- ▶ expert knowledge required  $\Rightarrow$  problematic for automation, new products
- ▶ artificial policies  $\Rightarrow$  inconsistencies
- ▶ no projection data taken into account

## Monte Carlo methods

- ▶ consider location variables  $y_j^{(i)}$ ,  $j = 1, \dots, M$ ,  $i = 1, \dots, m$  of the model points and  $y_1^{(P)}, \dots, y_M^{(P)}$  of the whole portfolio
- ▶ draw a sample of  $m$  policies and optimize their weights  $x_1, \dots, x_m \geq 0$  to solve

$$||A \cdot x - b|| \rightarrow \min,$$

$$A = \begin{pmatrix} y_1^{(1)} & y_1^{(2)} & \dots & y_1^{(m)} \\ y_2^{(1)} & y_2^{(2)} & \dots & y_2^{(m)} \\ \vdots & \vdots & & \vdots \\ y_M^{(1)} & y_M^{(2)} & \dots & y_M^{(m)} \end{pmatrix}, \quad x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix}, \quad b = \begin{pmatrix} y_1^{(P)} \\ y_2^{(P)} \\ \vdots \\ y_M^{(P)} \end{pmatrix}$$

## Clustering

- ▶ model each policy  $C_i$  as a data point in  $\mathbb{R}^M$  w.r.t. its location variables  $y_1^{(i)}, \dots, y_M^{(i)}$
- ▶ identify  $m$  disjoint homogeneous clusters of policies w.r.t a distance measure, e.g.

$$d(C_i, C_k) = \sqrt{\sum_{j=1}^M \left( y_j^{(i)} - y_j^{(k)} \right)^2}$$

Applied clustering methods in the context of compression:

- ▶ hierarchical clustering, e.g. Ward's method
  - ▶ partitional clustering, e.g. k-means
  - ▶ model-based-clustering, e.g. EM-algorithm
- ⇒ choice of one representative model point per cluster

## Validation: general aspects

- ▶ Underlying projection data of validation

$$\left\{ \{y_{jts}^{(P)}\}, \{y_{jts}^{(P_1^{MP})}\}, \dots, \{y_{jts}^{(P_R^{MP})}\}, j \in \mathcal{Q}, t \in \mathcal{T}, s \in \mathcal{S} \right\}.$$

- ▶ compression quality depends on homogeneity of portfolio
- ▶ check compression ratio and structure of compressed portfolio [1]
- ▶ static validation: compare portfolio key figures, cash flows and balance sheet items at the valuation date
- ▶ dynamic validation: [6]
  - ▶ forward validation: compare future projection values
  - ▶ backward validation: projection for previous period and comparison with portfolio at valuation date
- ▶ validate within-sample or out-of-sample

## General requirements towards a validation function

- ▶ **Completeness:** incorporate all aspects being part of the main goals of the compression
- ▶ **Expediency:** quantify the compression quality by using adequate methods w.r.t the goals of the compression
- ▶ **Non-redundancy:** similar aspects should not be considered simultaneously in order not to overstate their impact on the validation
- ▶ **Balance:** not only multiple aspects combined should not dominate the validation function, but also single aspects should not become too influential in comparison to others

## Validation function

Assume  $y_{jts}^{(P)} \cdot y_{jts}^{(P^{MP})} > 0, j \in \mathcal{Q} = \mathcal{Q}_1 \cup \mathcal{Q}_2, t \in \mathcal{T}, s \in \mathcal{S}$ :

$$d_{\mathcal{Q}, \mathcal{T}, \mathcal{S}}(P, P^{MP}) =$$

$$\left( \sum_{j \in \mathcal{Q}_1} \sum_{t \in \mathcal{T}} \sum_{s \in \mathcal{S}} w_j g_t^j f_s \left| \log \left( \frac{y_{jts}^{(P^{MP})}}{y_{jts}^{(P)}} \right) \right|^p \right)^{\frac{1}{p}} + \alpha \cdot g_{\mathcal{Q}, \mathcal{T}, \mathcal{S}}(P, P^{MP})$$

where  $p \geq 1, \alpha \geq 0$ , weights  $w_j \geq 0, g_t^j \geq 0, f_s \geq 0$ .

Violation of constraints  $h_{\mathcal{Q}, \mathcal{T}, \mathcal{S}}(P, P^{MP})_k \leq 0$  is penalized

$$g_{\mathcal{Q}, \mathcal{T}, \mathcal{S}}(P, P^{MP}) =$$

$$\left( \sum_{k \in \mathcal{Q}_2} \sum_{t \in \mathcal{T}} \sum_{s \in \mathcal{S}} w_k g_t^k f_s \left| \log \left( \frac{y_{kts}^{(P^{MP})}}{y_{kts}^{(P)}} \right) \right|^p \cdot \mathbb{1}_{\{h_{\mathcal{Q}, \mathcal{T}, \mathcal{S}}(P, P^{MP})_k > 0\}} \right)^{\frac{1}{p}}.$$

## Properties of validation function

- ▶ function constitutes a metric on  $\mathcal{P}$
- ▶ in line with the theory of multiple criteria decision making (MCDM) [2,4,5,9]

Advantages of logarithm:

$$\log \left( \frac{y_{jts}^{(PMP)}}{y_{jts}^{(P)}} \right) \approx \frac{y_{jts}^{(PMP)} - y_{jts}^{(P)}}{y_{jts}^{(PMP)}} \text{ for } \left( \frac{y_{jts}^{(PMP)}}{y_{jts}^{(P)}} \right) \rightarrow 1$$

- ▶ general form of relative deviations with useful properties [8]
- ▶ limits the problem that relative deviations w.r.t. small values can become very large



## Calibration of parameters: idea

- ▶ calibrate parameters to underlying validation data in order to ensure non-redundancy and balance of validation function
- ▶ no calibration necessary for  $p$
- ▶ set  $g_t^j$ ,  $t \in \mathcal{T}$ ,  $j \in \mathcal{Q}$ , and  $f_s$ ,  $s \in \mathcal{S}$ , according to relevance
- ▶ compose  $w_j$ ,  $j \in \mathcal{Q}$ , from factors representing its relevance, correlation with other figures (non-redundancy) and the magnitude of its deviations (balance)
- ▶ determine  $\alpha$  such that the two parts of the validation function represent a reasonable ratio (balance)

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